

Safety and Time Critical Middleware for future Modular Avionics Platform

Ahmad AL SHEIKH -- 1st Year PhD student (MRS/OLC)

Directors:

Olivier BRUN (MRS)

Pierre-Emmanuel HLADIK (OLC)

Seminar SINC -- 28/04/2009

SATRIMMAP

- ❑ ANR research project.
- ❑ Partners: Airbus, CEA, IRIT, LAAS, ONERA, QoS Design.



The Architecture

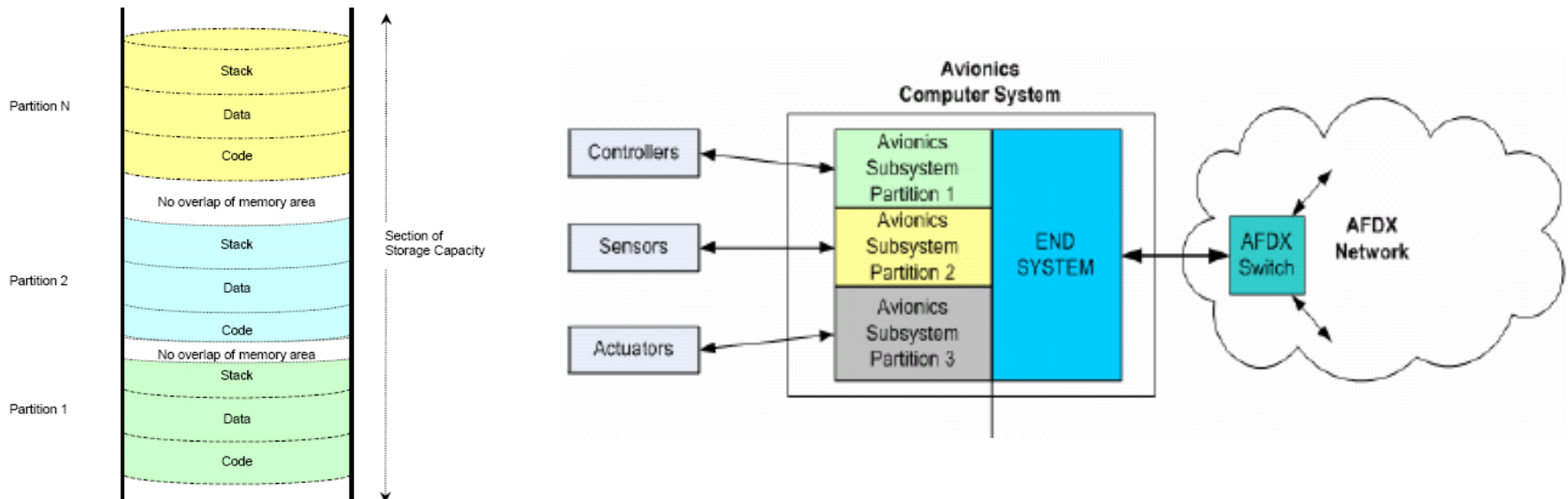


The IMA Architecture

- ▶ **Integrated Modular Avionics**
 - ▶ Interconnection of several modules/embedded systems on one platform.
 - ▶ Sharing resources and bandwidth.
- ▶ **Several computing modules capable of supporting numerous applications of different criticality.**
- ▶ **Modules include:**
 - ▶ CPM: Core processing modules.
 - ▶ CPIOM: Core processing and I/O modules.
 - ▶ RDC: Remote data concentrator.

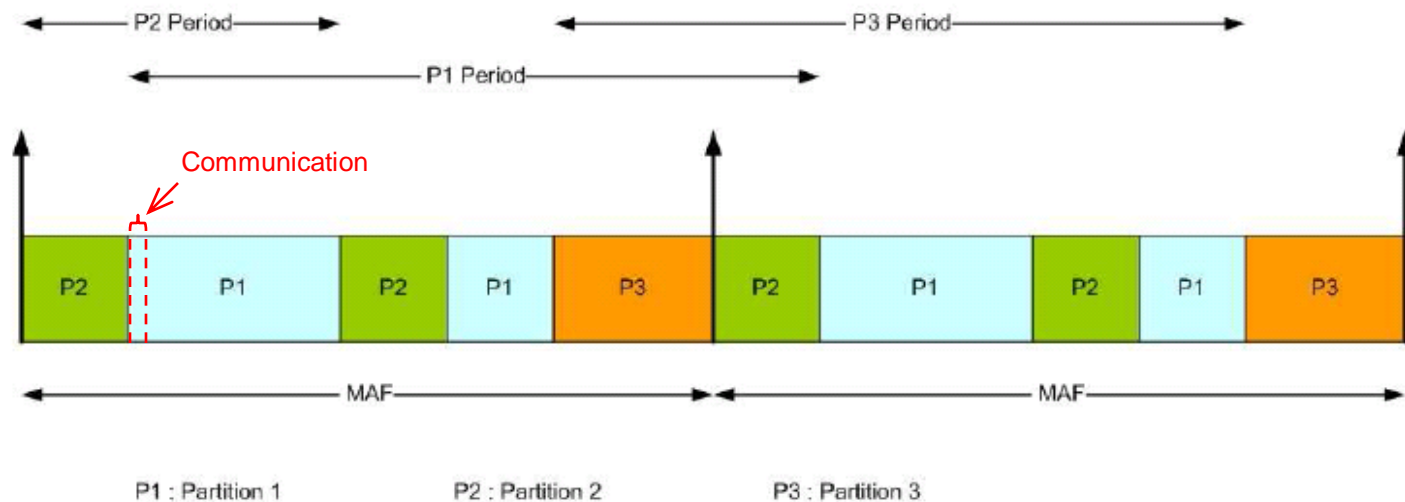
Avionics Applications and Partitions

- ▶ Several applications resident on a computer system
 - ▶ Applications broken up to one or more partitions (pieces of code, data,...) based on criticality variation of its operation
 - ▶ Separation in resources and influence by communication only
 - ▶ Communication with partitions resident on other computer systems is through AFDX network via ports and an interface (End System)



Partitions

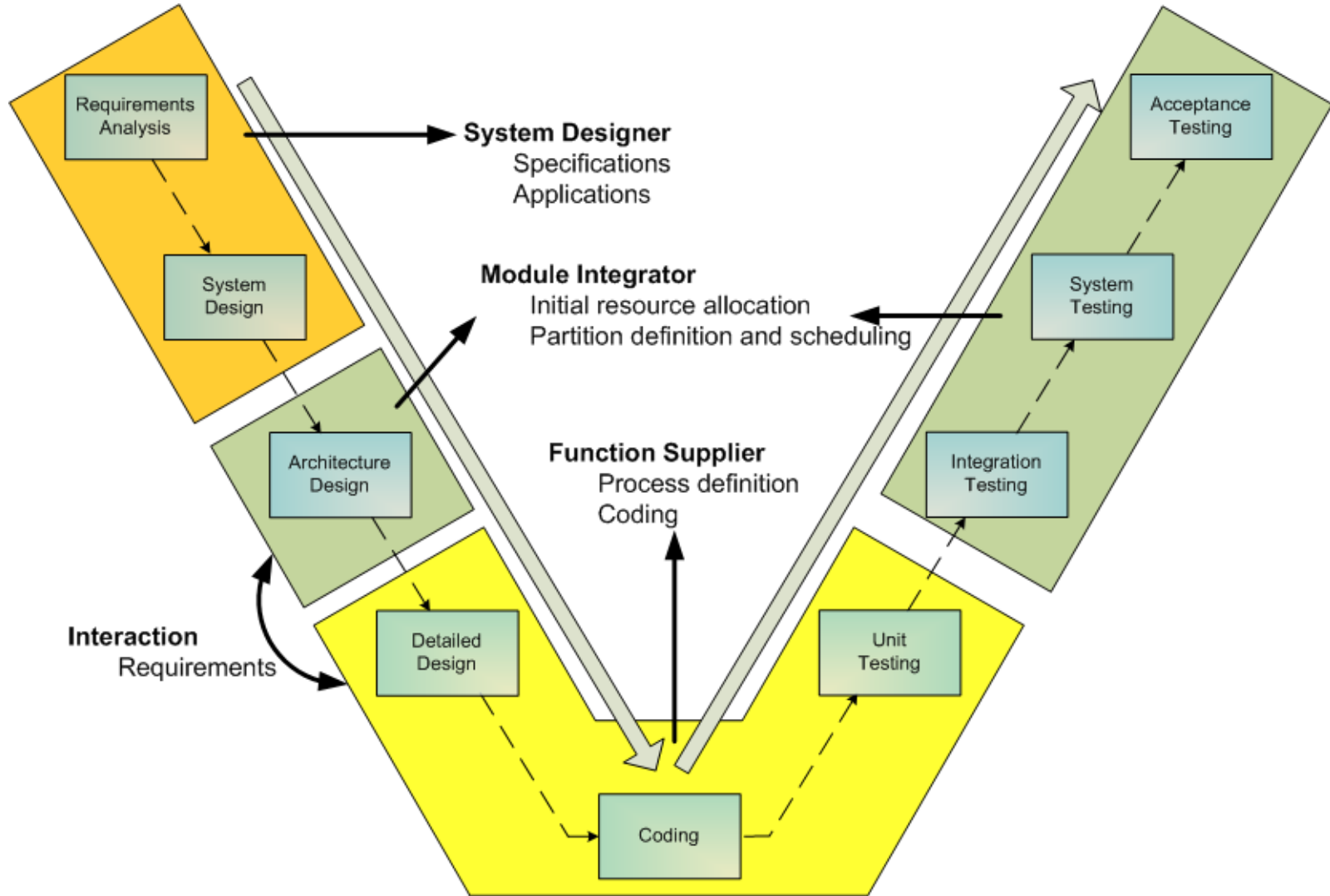
- ▶ Partitions have no priority and are periodic
- ▶ Scheduling algorithm of partitions is static with fixed periodicity
- ▶ Each partition allocated a window for execution



Processes

- ▶ Partitions comprised of one or more processes
- ▶ Processes have priorities defined statically, hence can preempt each other
- ▶ Processes may be periodic, aperiodic or sporadic
- ▶ Processes allowed to execute in corresponding partition window
- ▶ Processes of same partition share resources and communicate via buffers, semaphores,...
- ▶ Processes belonging to different partitions communicate via sampling/queuing ports

Software Development Cycle (AIRBUS)



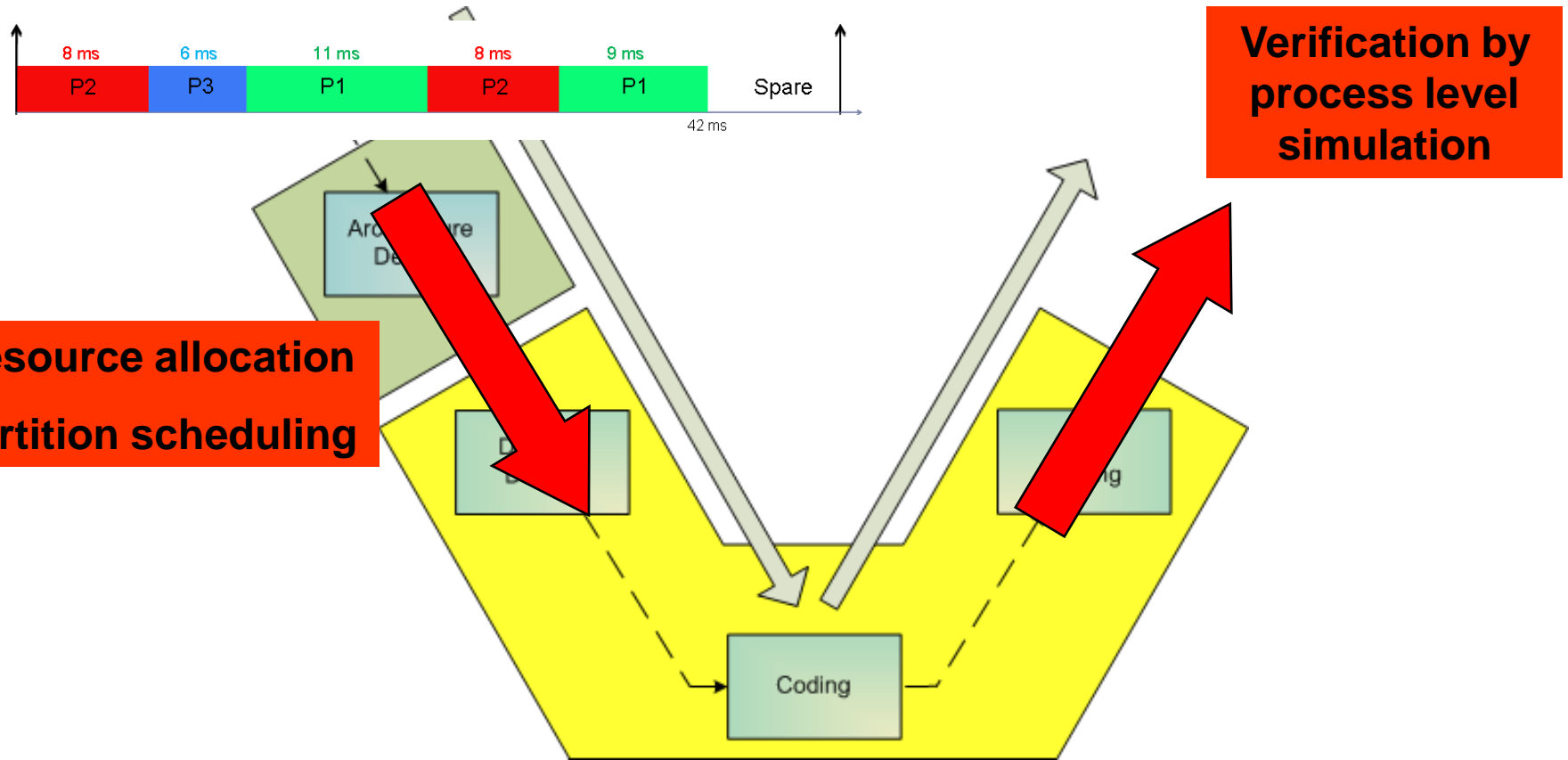
Objectives



Objectives

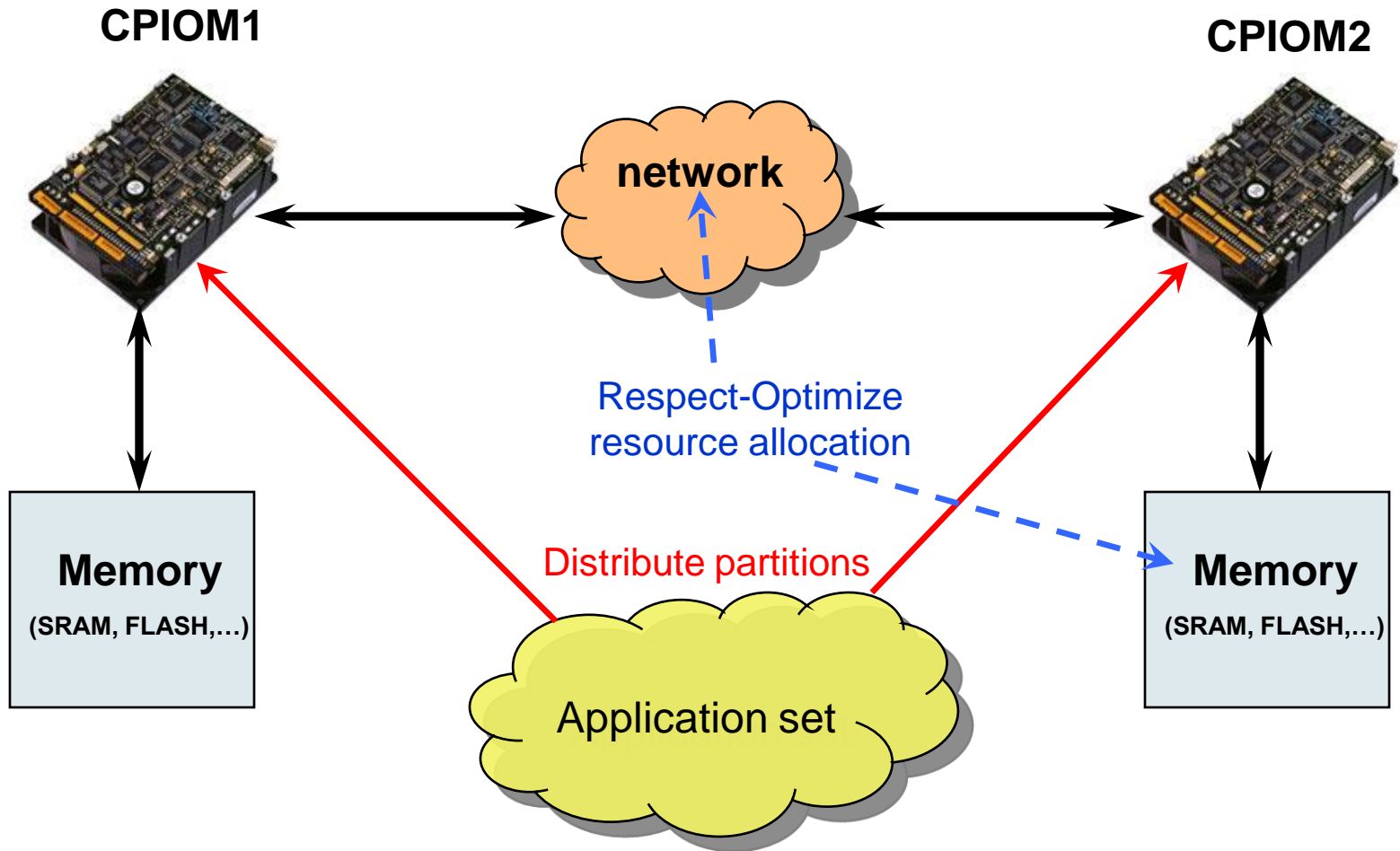
- ▶ Initial demand: develop a simulation and evaluation tool which is the primary requirement of our work
- ▶ Identifying the goals of the simulation
 - ▶ Feasibility of a system that is designed to be so
- ▶ Propose the introduction of new functional aspects to our tool
 - ▶ Aiding the designer in constructing the system
 - ▶ Resource mapping and scheduling
 - ▶ Propose possible and optimal solutions

Contribution (aimed for)



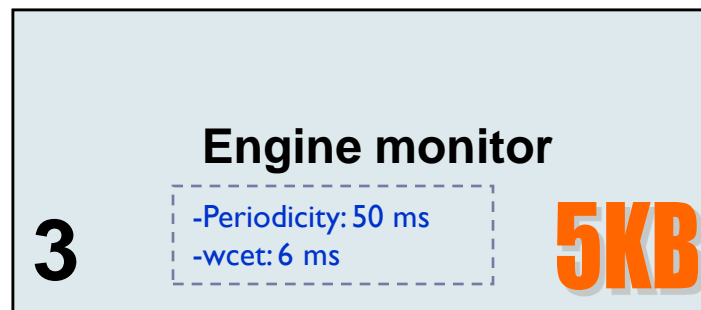
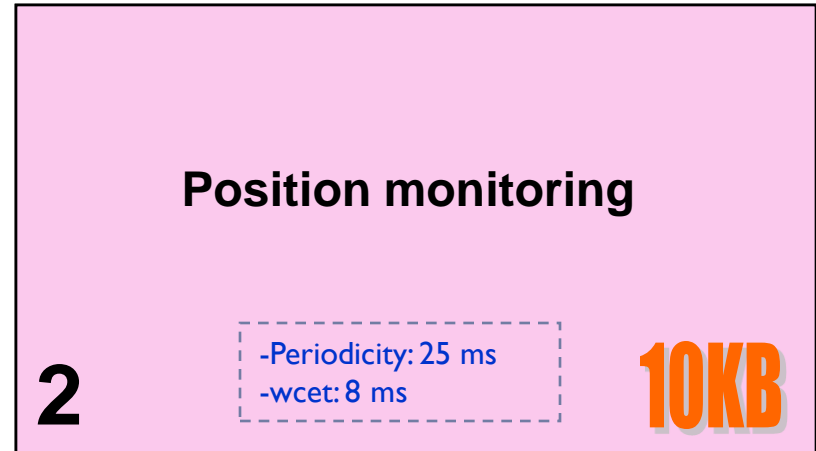
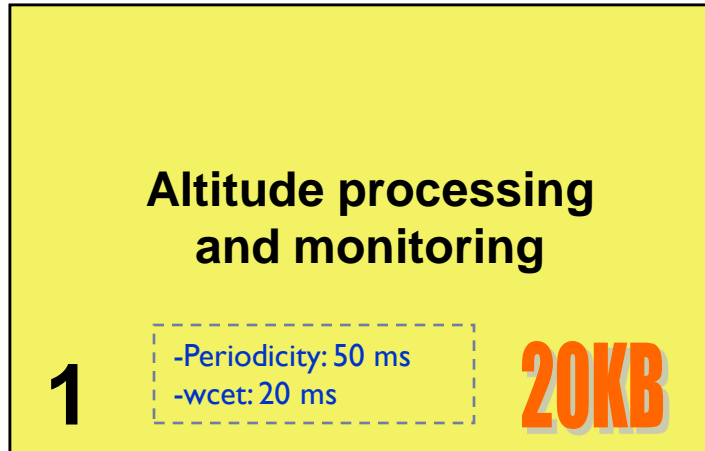
An Example

Environment



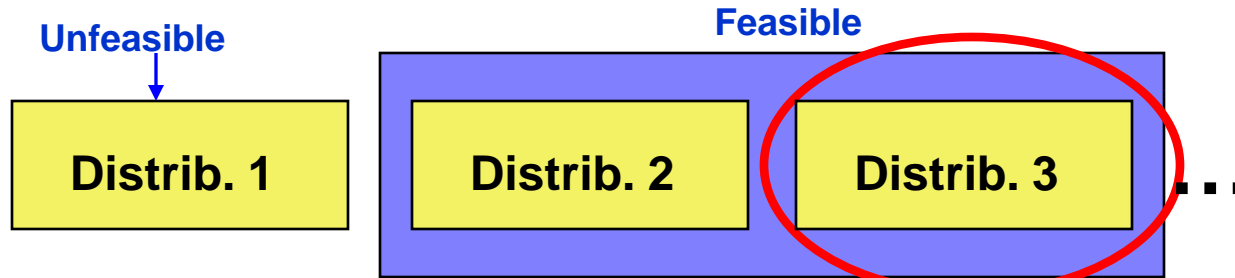
Partition Example

- ▶ Application set: For simplicity, only memory as resource constraint

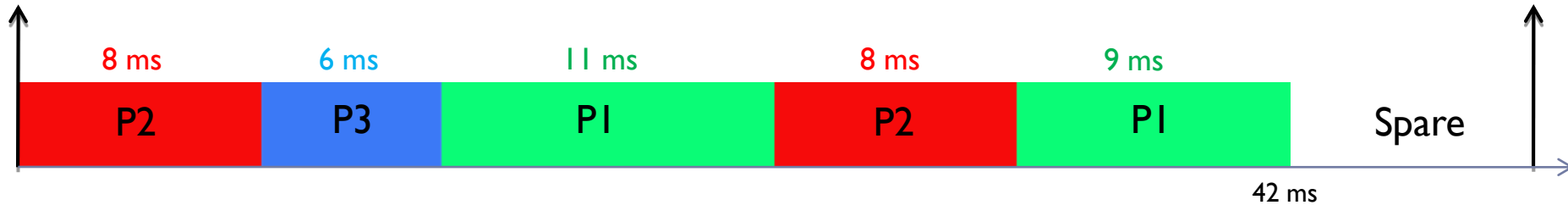


Distribution of partitions

- ▶ Choose suitable distribution respecting constraints



1. Search for feasible solutions
2. Select optimum



Process Scheduling Verification

▶ Process execution simulation:



Conclusion

Conclusion

- ▶ Define applications + attributes
- ▶ Provide a model for our constraints (partitions, resources, network, etc...)
- ▶ Study possible algorithms to solve our distribution and scheduling problem [*thesis-Roux*].
- ▶ After corresponding partition configuration, wait for process definition.
 - ▶ Simulate the execution of processes with the above mentioned partition configuration.
- ▶ Prospective → Break down partitions into functions