



Limited Discrepancy Search for flexible shop scheduling

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Objectives

- Some **research results** in solving **scheduling problems**, central in supply chain management
- Emphasis on **flexible shop problems**
- Adapting **discrepancy-based search methods** for the problems under study
- **Experimental evaluation** of the propositions



Scheduling Problems under study

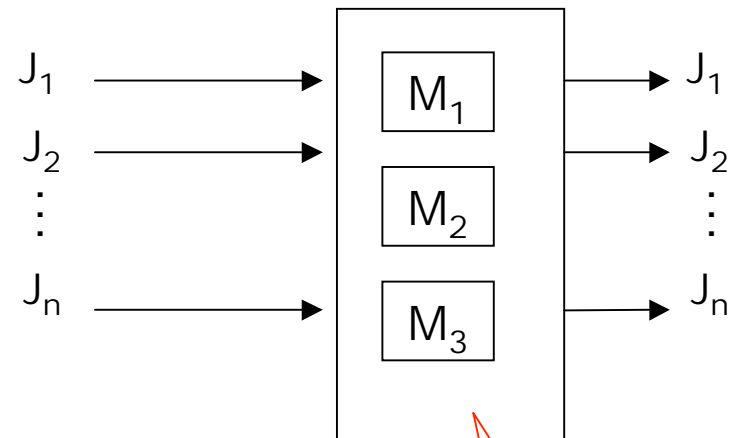
- Disjunctive scheduling
 - Resources = machines
 - One operation at a time on a machine
 - One machine at a time by operation
 - No preemption
 - Shop problems
 - Execution route (routing) = sequence of machines to follow to manufacture a product
 - Job = sequence of operations following a given route
- Focus on *flexible* shop problems
 - Resource assignment is **not** decided *a priori*
 - Parallel Machine
 - Hybrid Flow Shop (HFS)
 - Flexible Job Shop (FJS)



Parallel machine



Job \equiv Operation



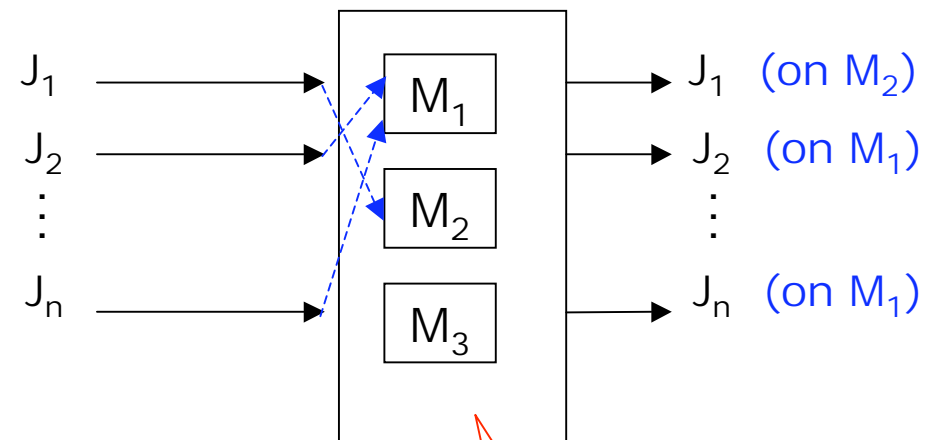
Allocation problem



Parallel machine



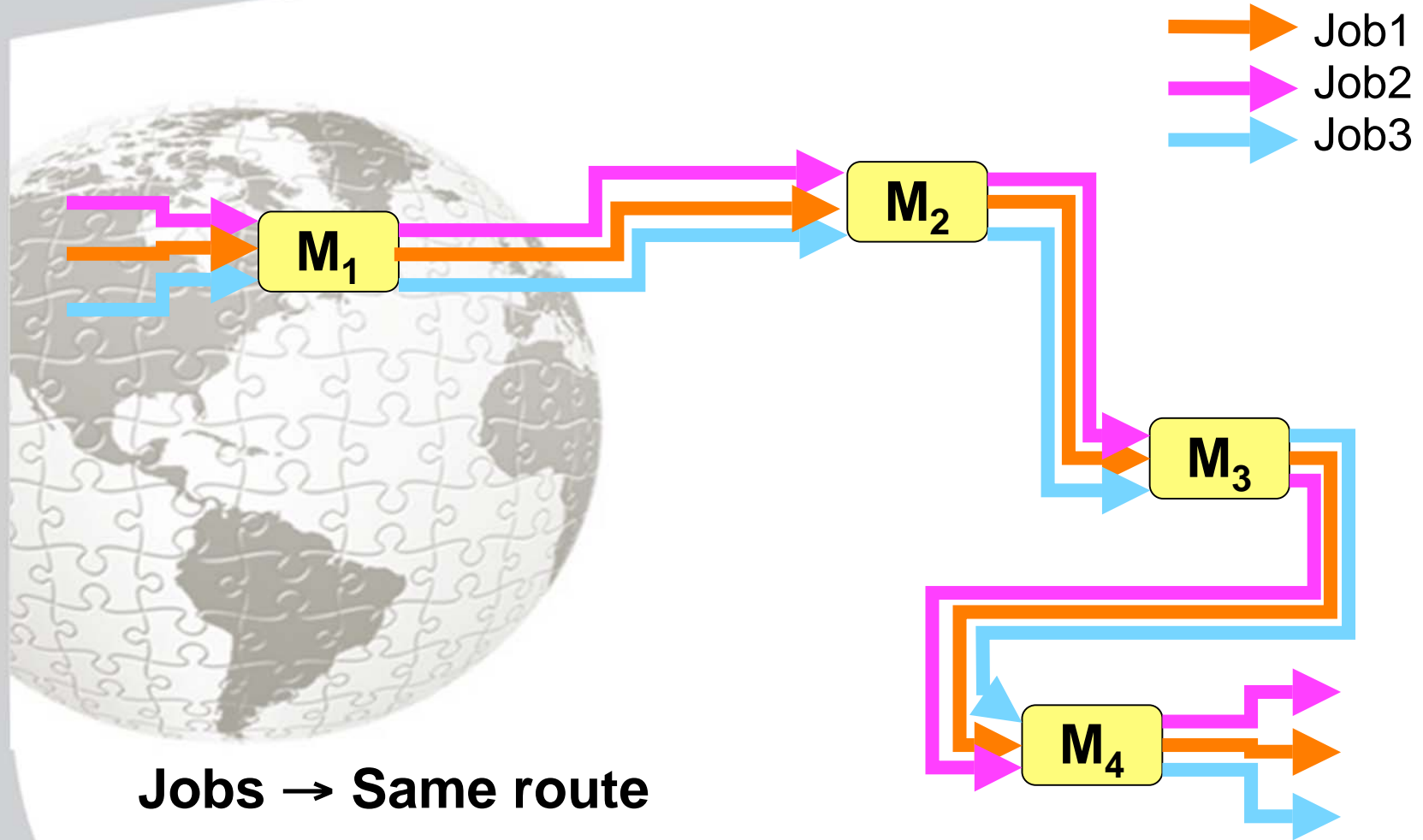
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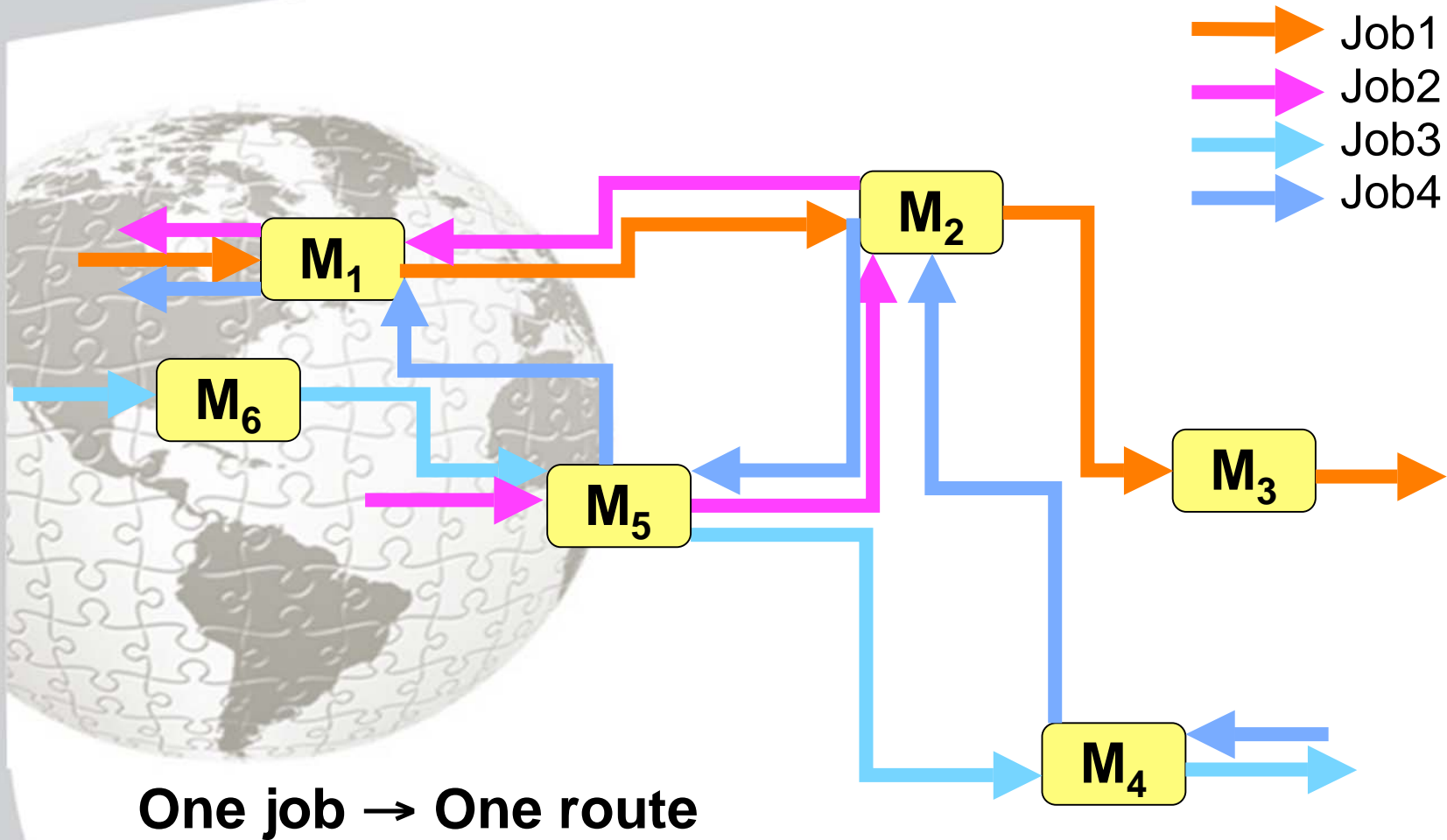
Allocation problem



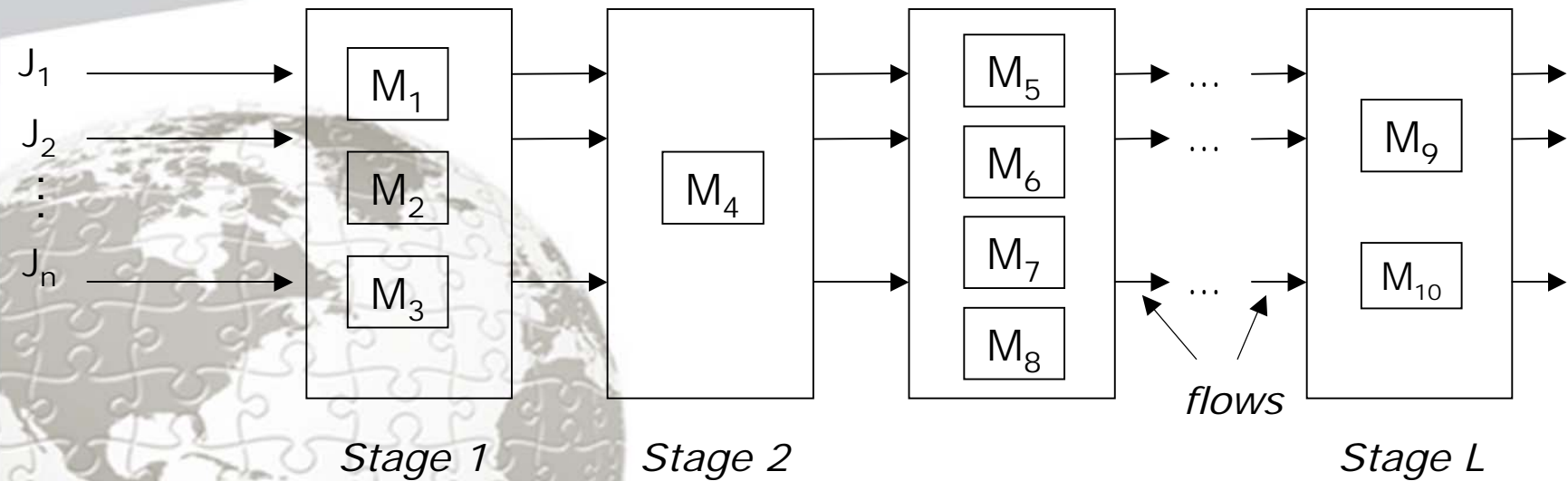
Shop problems: Flow Shop



Shop problems: Job Shop



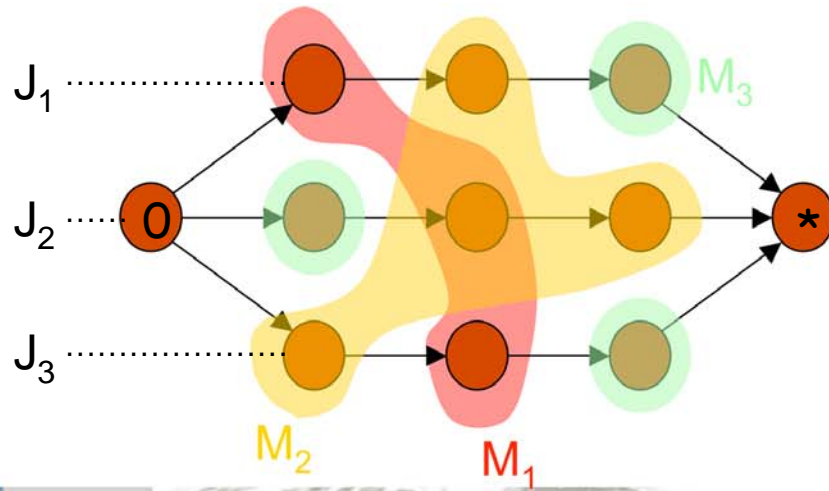
Shop problems: Hybrid Flow Shop



- ❑ $J = \{J_1, \dots, J_i, \dots, J_n\}$ jobs
- ❑ $E = \{1, \dots, s, \dots, L\}$ stages
- ❑ $M^{(s)}$: identical parallel machines / $\max(M^{(s)}) > 1$
- ❑ Application: semiconductors

(Printed Circuit Boards)

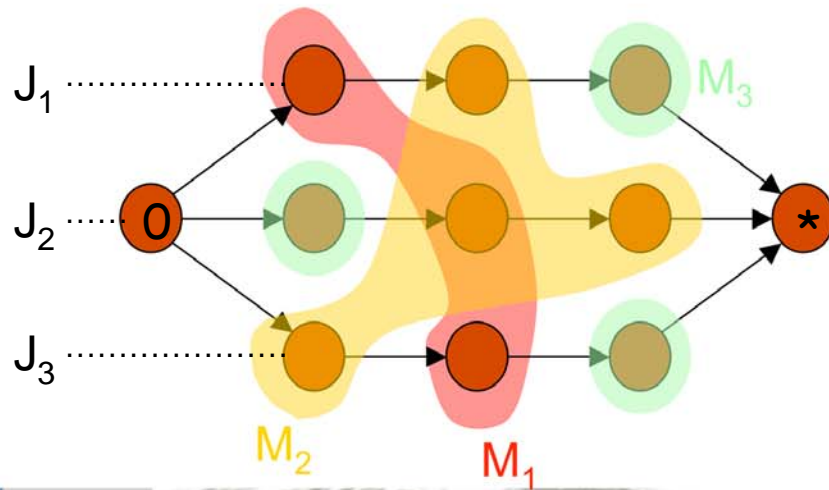




Shop pbs: Flexible Job Shop

- As in a Job Shop:
 - Resources = machines: $M = \{M_1, \dots, M_m\}$
 - Job $J_i =$ sequence of operations O_{i1}, \dots, O_{im}



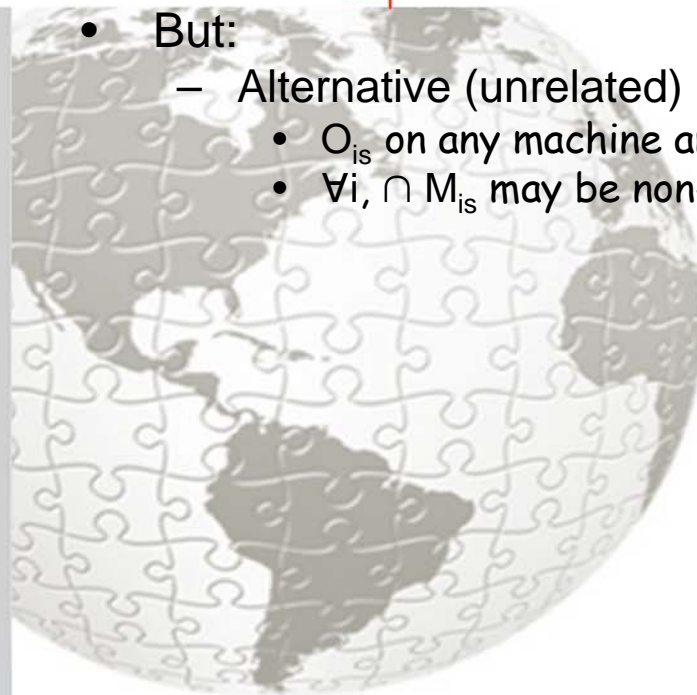


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 - Resources = machines: $M = \{M_1, \dots, M_m\}$
 - Job $J_i =$ sequence of operations O_{i1}, \dots, O_{im}

- But:

- Alternative (unrelated) machines can process an operation
 - O_{is} on any machine among $M_{is} \subseteq M$;
 - $\forall i, \cap M_{is}$ may be non-empty ("recirculation")

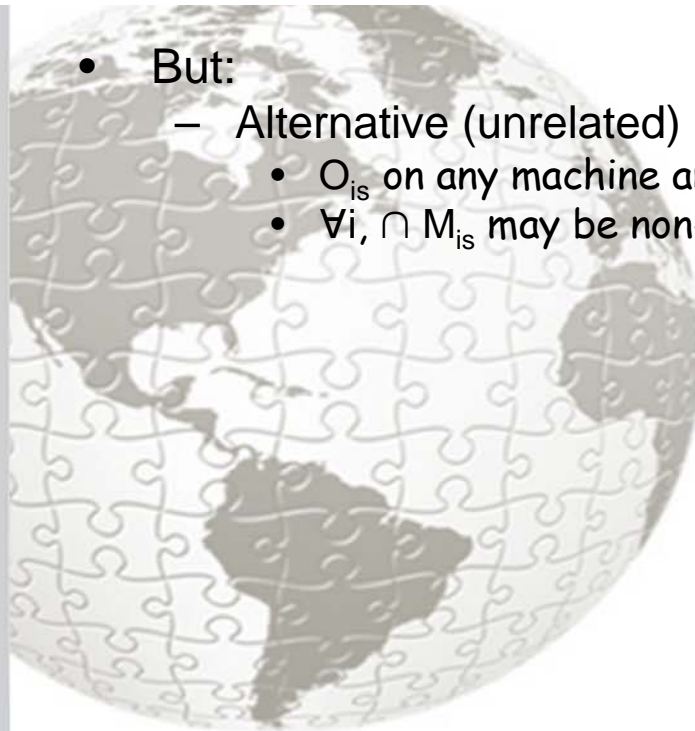


	M_{21}	M_{22}	M_{23}
J_2 :	$M_1(20)$ or $M_2(25)$	$M_1(25)$	$M_1(30)$ or $M_2(15)$ or $M_3(25)$

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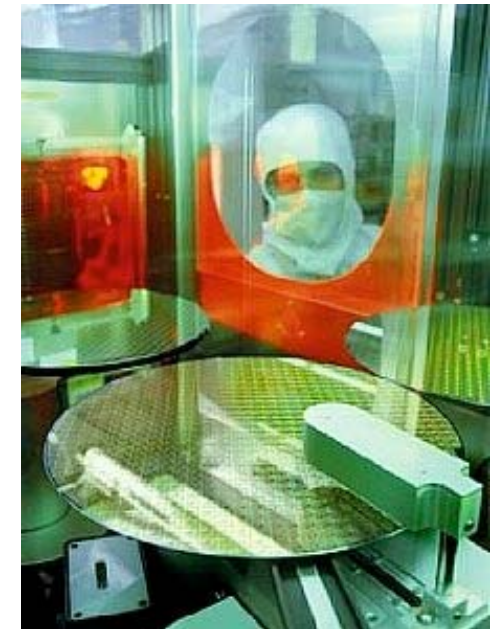
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- But:
 - Alternative (unrelated) machines can process an operation
 - O_{is} on any machine among $M_{is} \subseteq M$;
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- Application: semiconductor industry (wafer fabrication)
- Double problem:
 - Select a machine for each operation
 - Determine a start time for each operation

$$\min C_{\max}$$



Solving scheduling problems

- **Exact methods**
 - dynamic programming
 - integer programming
 - tree search
- **Heuristics**
 - dispatching rules
 - greedy algorithms
- **Metaheuristics**
 - Tabu search
 - genetic algorithms
 - ant colony optimization
- **Constraint programming**



Solving scheduling problems

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Background

- *NP-hard* problems [Vaessens, 1995]
- Hybrid Flow Shop (HFS)
 - 2-HFS with $M^{(s)}=2$ for $s \in \{1,2\}$ is NP-hard: [Gupta, 1988]
 - Exact methods: [Brah & Hunsucker, 1991]; [Portmann *et al.*, 1992]; [Moursli & Pochet, 2000]; [Carlier & Néron, 2000]; [Lin & Liao, 2003]
 - Lower bounds: [Santos *et al.*, 1995]; [Moursli & Pochet, 2000]; [Carlier & Néron, 2000]
 - Heuristics: [Brah & Loo, 1999]; [Engin & Döyen, 2004]
- Flexible Job Shop (FJS)
 - First presented by [Brucker & Schlie, 1990]
 - FJSP is NP-Hard in general [Vaessens, 1995]
 - Greedy and GA algorithms were proposed (many references)
 - Best results obtained by Tabu Search [Mastrolilli & Gambardella, 2000]
 - JMPM || C_{\max} is strongly NP-hard [Brucker, 2004]



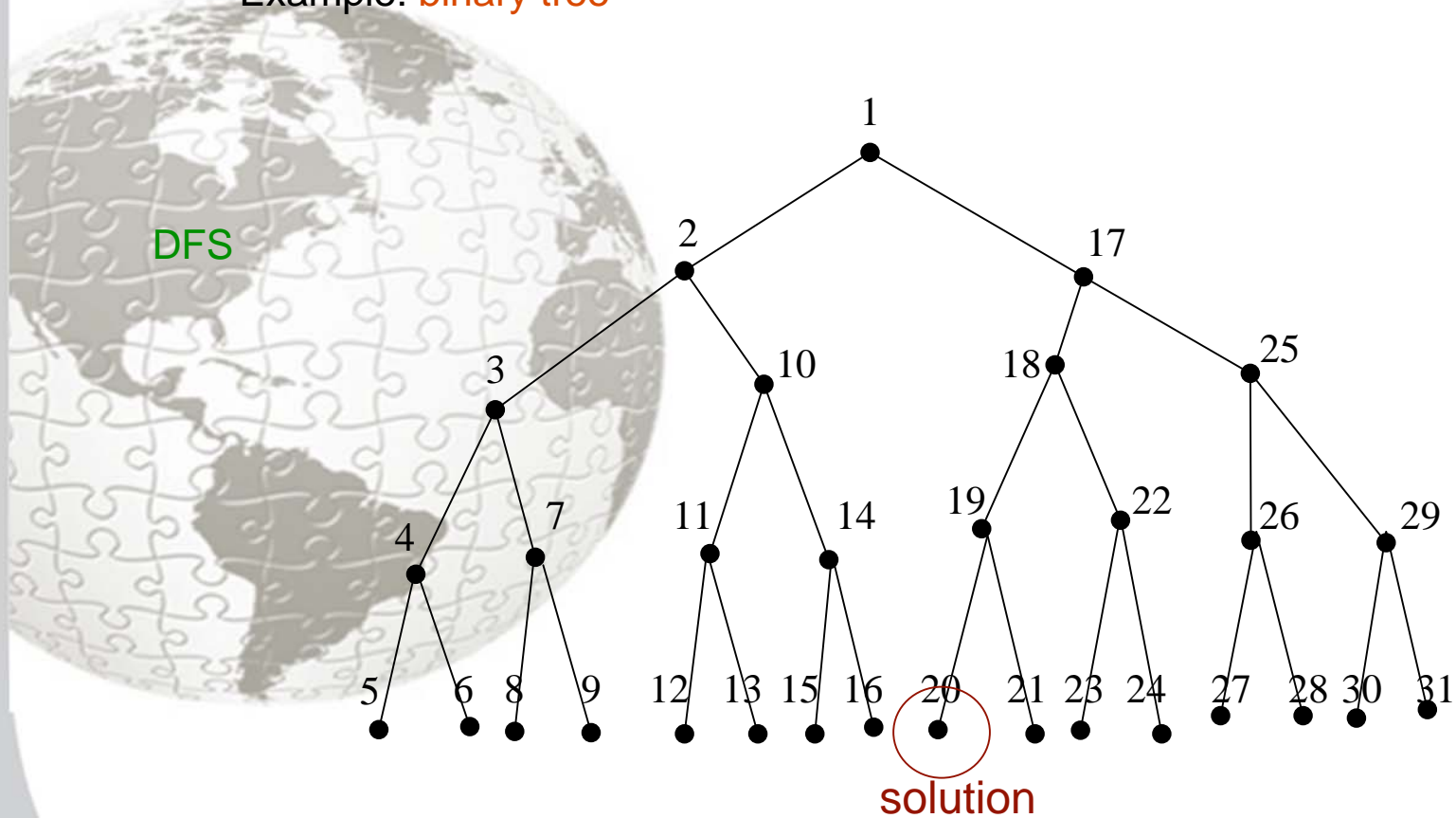
Discrepancy-based search methods (1)

- Limited Discrepancy Search - LDS [Harvey & Ginsberg, 1995]
 - Is a problem satisfiable? → *Satisfaction*
 - Iterative tree search method
 - Instantiation heuristic to guide the search
(the initial global instantiation is not necessarily a solution)
 - When the heuristic does not find a good solution, it is probably because it made a few poor choices → *discrepancy* then makes a choice different than heuristically top-ranked
 - Hope to find a solution before *Depth-First Search*



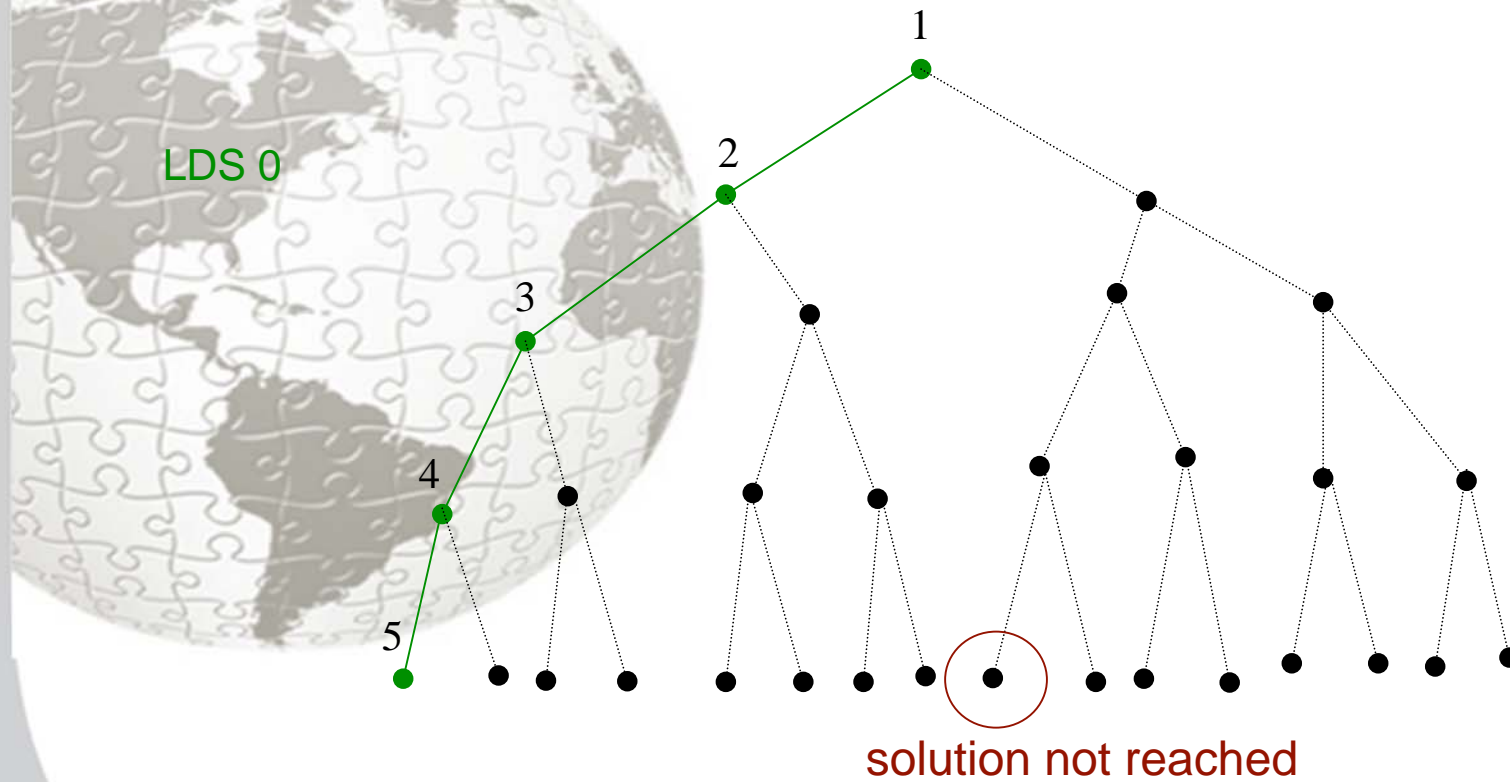
Depth First Search (DFS)

- Search principle
 - Example: **binary tree**



Limited Discrepancy Search (LDS)

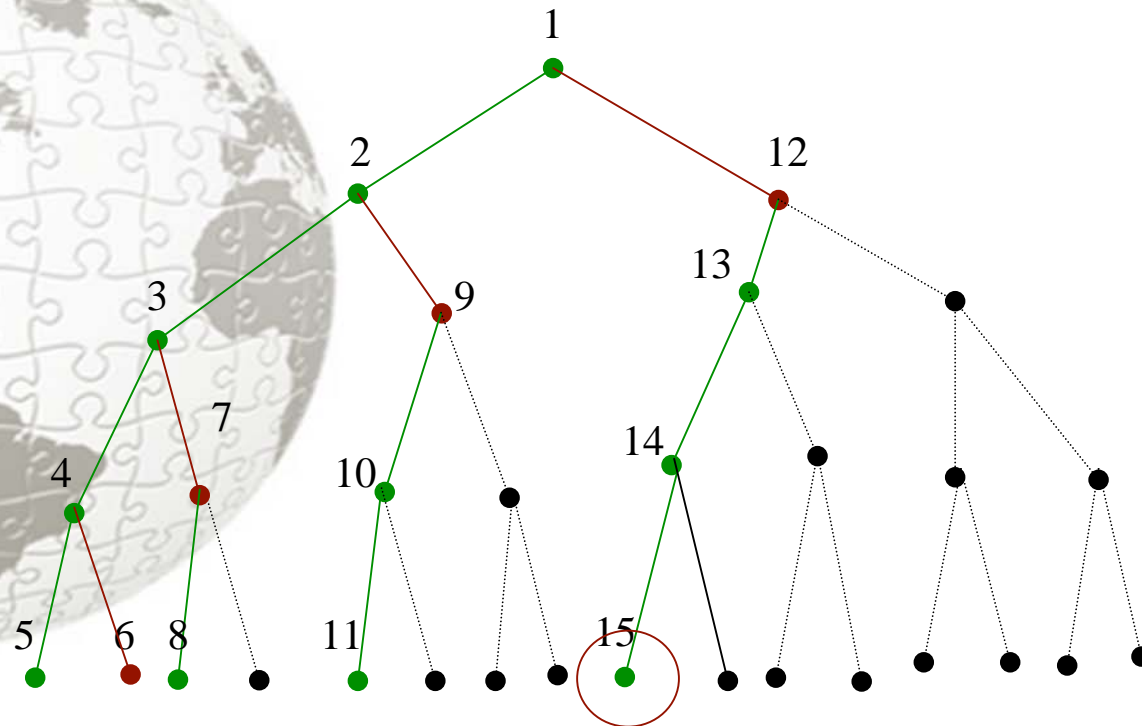
- Search principle
 - Example: **binary tree**
 - LDS 0: The choices of the heuristic are satisfied



Limited Discrepancy Search (LDS)

- Search principle
 - Example: **binary tree**
 - LDS 1: All the paths differ of ONE decision from LDS 0

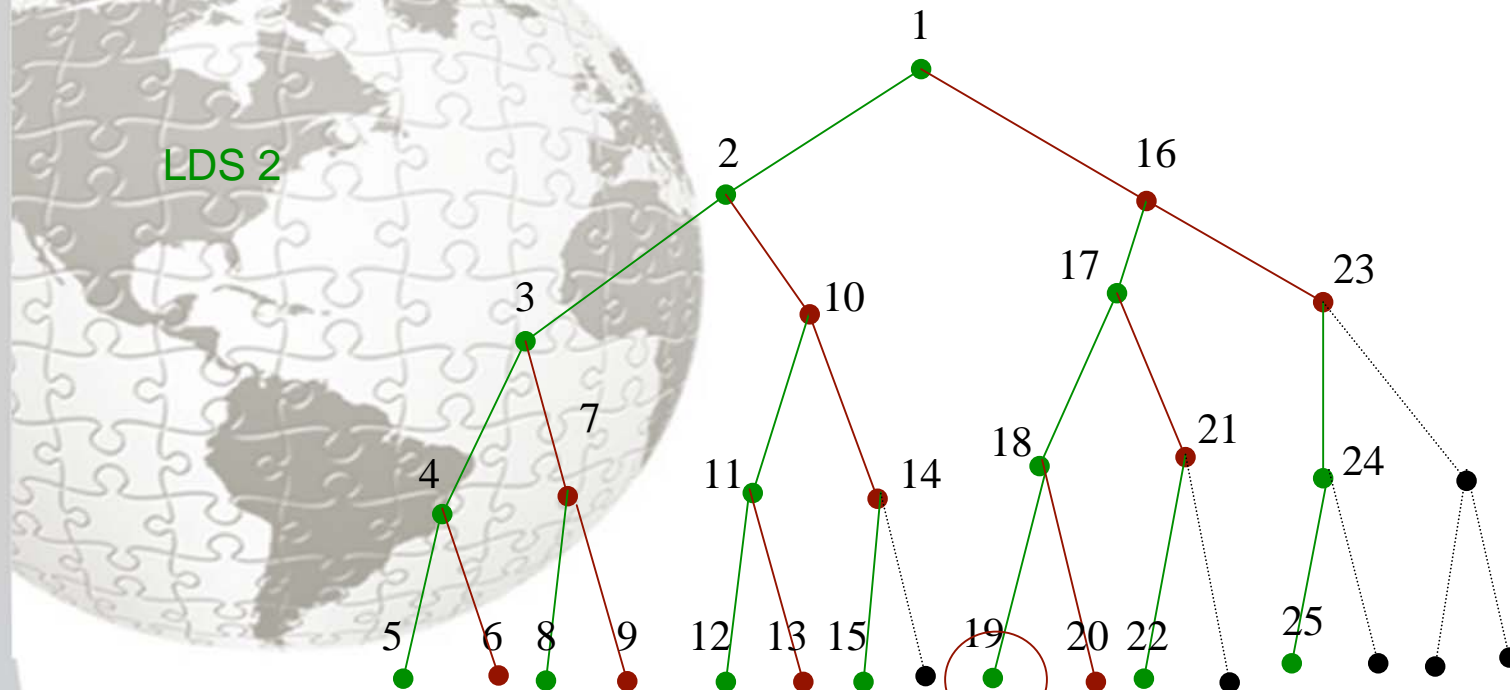
LDS 1



solution reached before DFS

Limited Discrepancy Search (LDS)

- Search principle
 - Example: **binary tree**
 - LDS 2: All the paths differ of TWO decisions (for TWO variables) from LDS 0

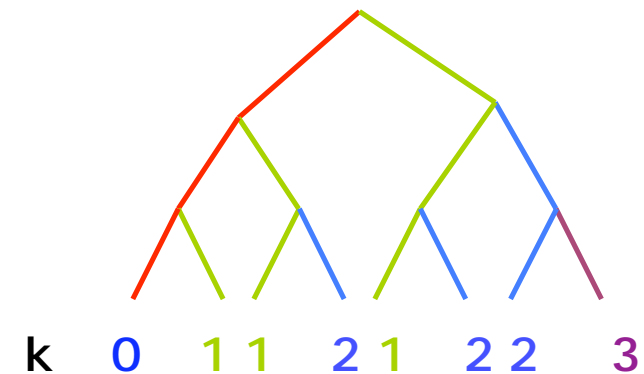


(Improved) Limited Discrepancy Search (I-LDS)

[\[Harvey & Ginsberg, 1995\]](#) and [\[Korf, 1996\]](#)

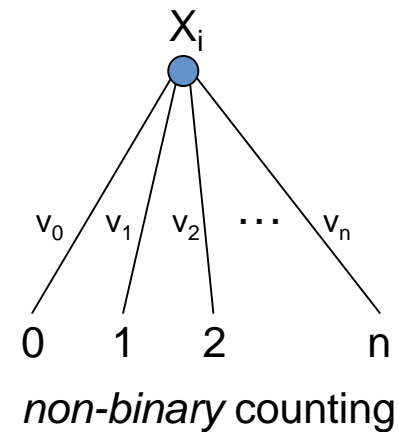
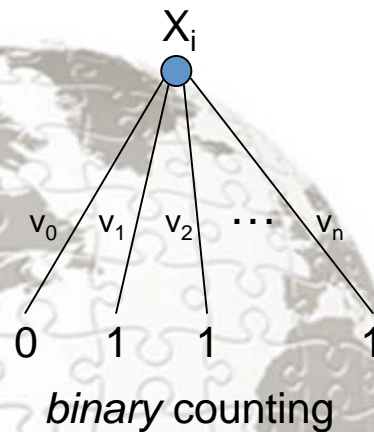
Algorithm

```
k ← 0
kmax ← N
I ← Initial_instantiation()
While no_solution() and (k ≤ kmax) do
  k ← k+1
  -- Generate leaves at discrepancy k from I
  -- Stop when a solution is found
  I ← compute_Leaves (I, k)
End while
```

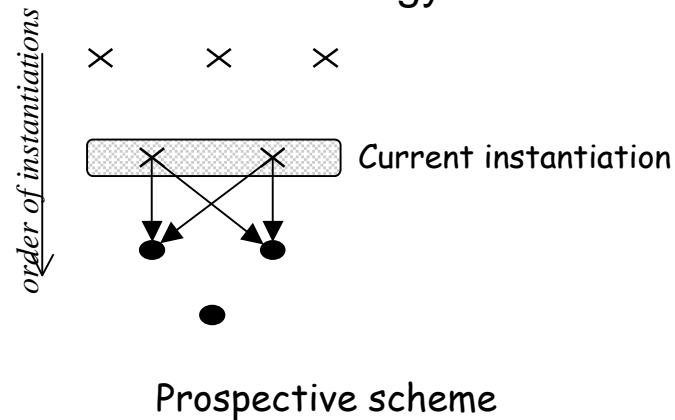


Discrepancy-based search methods (2)

- **Non-binary trees:** 2 ways for counting discrepancies

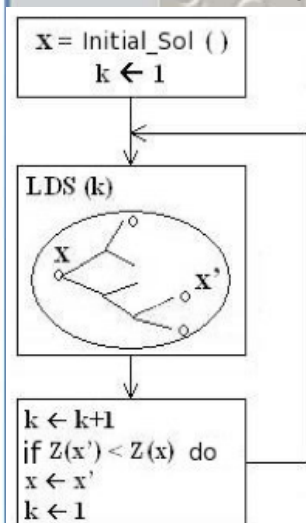


- The binary counting is adopted in our search strategy
- Local propagation by *Forward-Checking*



Discrepancy-based search methods (3)

- Depth-bounded Discrepancy Search - **DDS** [Walsh, 1997]
 - → *Satisfaction*
 - To correct “early mistakes” (the most important)
 - Principle: discrepancies on top of the search tree (given depth)
 - Stop: a solution is found
- Climbing Discrepancy Search - **CDS** [Milano & Roli, 2005]
 - To improve current solution → *Optimization*
 - Principle:
 - Initial solution (Reference)
 - Apply LDS principle to explore the neighborhood from this reference
 - Reference \leftarrow Improved_Solution
 - Restart with #discrepancy \leftarrow 0
 - Stop: no more improvement, limit on time or #iterations reached
 - CDS is close to VNS [Hansen & Mladenovic, 2001]



Proposed method: CDDS (1)

- To combine 2 discrepancy-based methods
 - Climbing DS (neighborhood search)
 - Depth-bounded DS (neighborhood restricted at the top of the tree)
 - *Climbing Depth-bounded Discrepancy Search (CDDS)*
- Optimization method: approximate solutions
 - Criterion = *makespan* minimization
 - A solution = UB
- LBs to fathom nodes in the search tree
- Example: HFS

$$\min C_{\max}$$

$$LB_l(i) = ct_{il} + \sum_{j=l+1}^k p_{ij} \quad (\text{where } ct_{il} \text{ is the completion time of } O_{il})$$

$$LBM[\text{Sch}^{(s)}(Y)] = \begin{cases} \text{ACT}[\text{Sch}^{(s)}(Y)] + \min_{i \in J-Y} \left\{ \sum_{s'=s+1}^L p_i^{(s')} \right\} & \text{if } \text{ACT}[\text{Sch}^{(s)}(Y)] > \text{MCT}[\text{Sch}^{(s)}(Y)] \\ \text{MCT}[\text{Sch}^{(s)}(Y)] + \min_{i \in Y} \left\{ \sum_{s'=s+1}^L p_i^{(s')} \right\} & \text{if } \text{ACT}[\text{Sch}^{(s)}(Y)] < \text{MCT}[\text{Sch}^{(s)}(Y)] \\ \text{ACT}[\text{Sch}^{(s)}(Y)] + \max \left\{ \min_{i \in J-Y} \sum_{s'=s+1}^L p_i^{(s')}, \min_{i \in Y} \sum_{s'=s+1}^L p_i^{(s')} \right\} & \text{if } \text{ACT}[\text{Sch}^{(s)}(Y)] = \text{MCT}[\text{Sch}^{(s)}(Y)] \end{cases} \quad (7)$$

Proposed method: CDDS (2)

- Exploration strategy
 - Instantiation heuristics
 1. Job selection: $X_i \in \{O_{11}, O_{12}, \dots, O_{1s_1}, O_{21}, \dots, O_{n1}, \dots, O_{ns_n}\}$
 11. Earliest Start Time (EST)
 12. SPT or EDD or LDJ (job of longest duration)
 2. Machine selection (allocation): $A_i \in \{M_1, \dots, M_m\}$
 - Earliest Completion Time (ECT)
 - Propagation = Forward-Checking over:
 - Start time of subsequent operations
 - Availability date of selected machine
 - Discrepancies
 - On job selection for HFS
 - On both types of variables (job and machine selection) for FJS



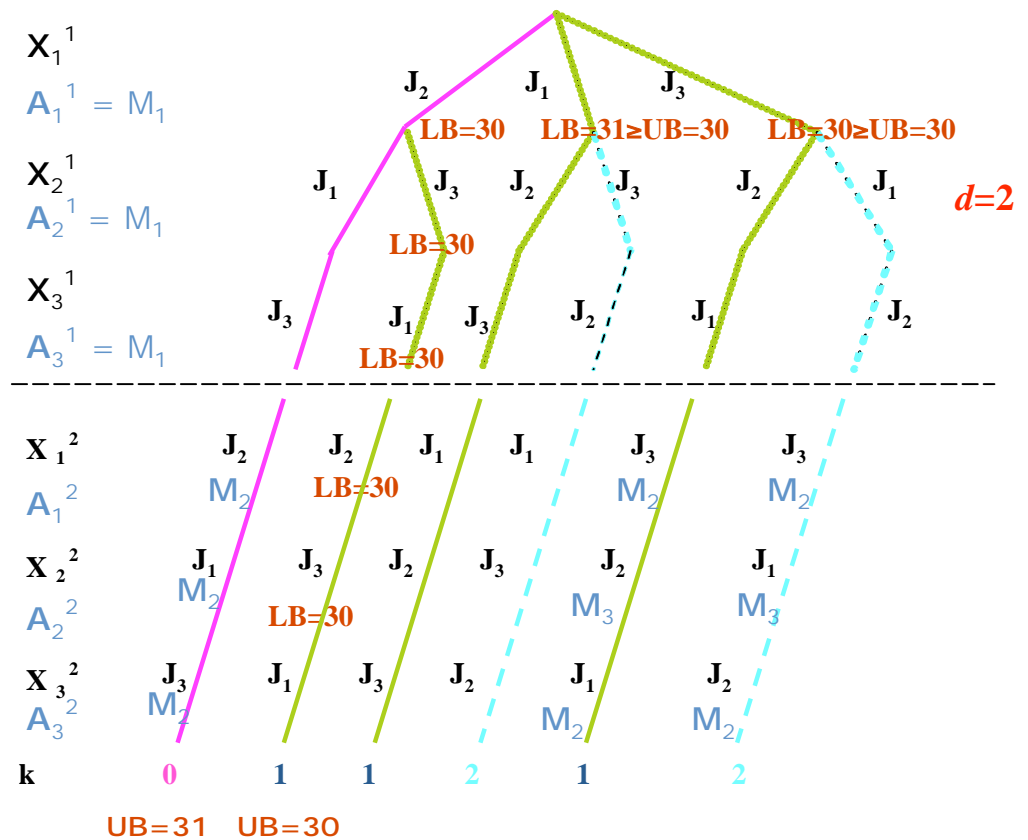
HFS: Example

Processing times of a 3x2 Hybrid Flow Shop

Jobs	Stage 1		Stage 2	
1	O_{11}	8	O_{12}	7
2	O_{21}	7	O_{22}	8
3	O_{31}	8	O_{32}	8

$$M^{(1)} = 1; M^{(2)} = 2$$

EST-SPT (1st stage):
 $J_2; J_1; J_3$

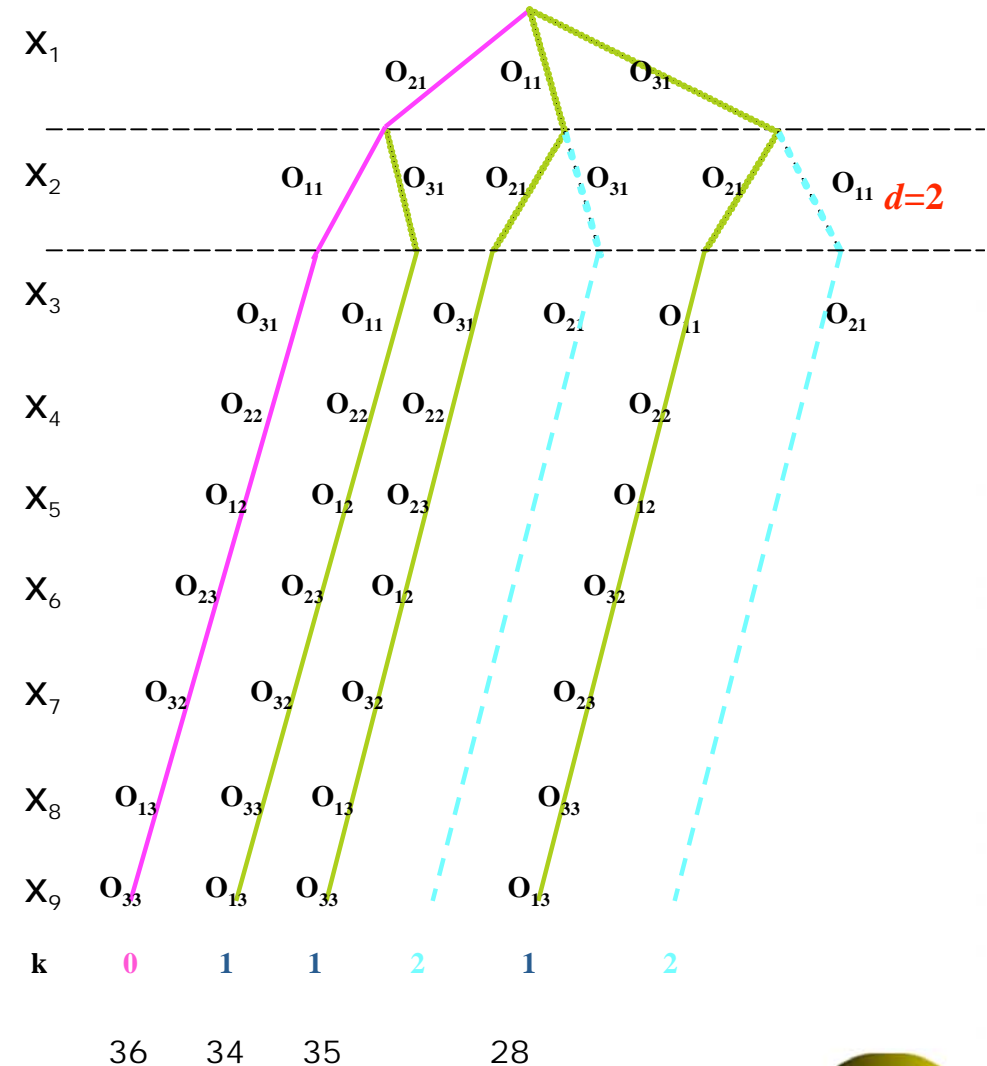


FJS: Example of discrepancy on job selection variable

Processing times of a 3×3 Flexible Job Shop

	M ₁	M ₂	M ₃
O ₁₁	--	8	--
O ₁₂	--	8	--
O ₁₃	--	6	--
O ₂₁	11	2	--
O ₂₂	--	3	10
O ₂₃	11	--	10
O ₃₁	12	--	12
O ₃₂	4	--	12
O ₃₃	12	--	--

EST-SPT: O₂₁; O₁₁; O₃₁



HFS: Experiments

- Instances:
 - Néron & Carlier
 - 52 easy problems
 - 24 hard problems
- Comparison:
 - LDJ is the best rule
 - B&B of [Néron & Carlier, 2000]
 - AIS
- Stop:
 - limit on CPU time=30 sec.

Relative performance of methods

<i>Method</i>	<i>easy</i>	<i>hard</i>	<i>all</i>
	<i>% deviation / LB</i>		
B&B	2.21	6.88	3.68
DDS	1.42	8.01	3.58
CDDS	1.1	5.0	2.32
AIS	1.01	3.12	1.68
CDDS^L	0.96	3.06	1.62

$$\% \text{ deviation} = \frac{C \max_best - \text{LowerBound}}{\text{LowerBound}} \times 100$$



2 stage-HFS: Experiments

- Instances:
 - Three sets generated in a similar way as [Lee & Vairaktarakis, 1994]
 - Set A: $S_1[1 - 20]$; $S_2[1 - 40]$
 - Set B: $S_1[1 - 40]$; $S_2[1 - 20]$
 - Set C: $S_1[1 - 40]$; $S_2[1 - 40]$
 - $n = \{10, 20, 30, 40, 50, 100, 150\}$: 1680 instances.
- Comparison:
 - LBs [Haouari *et al.*, 2006]
 - TS and LBs [Haouari & M'Hallah, 1997]
- Stop:
 - limit on CPU time=15 sec.

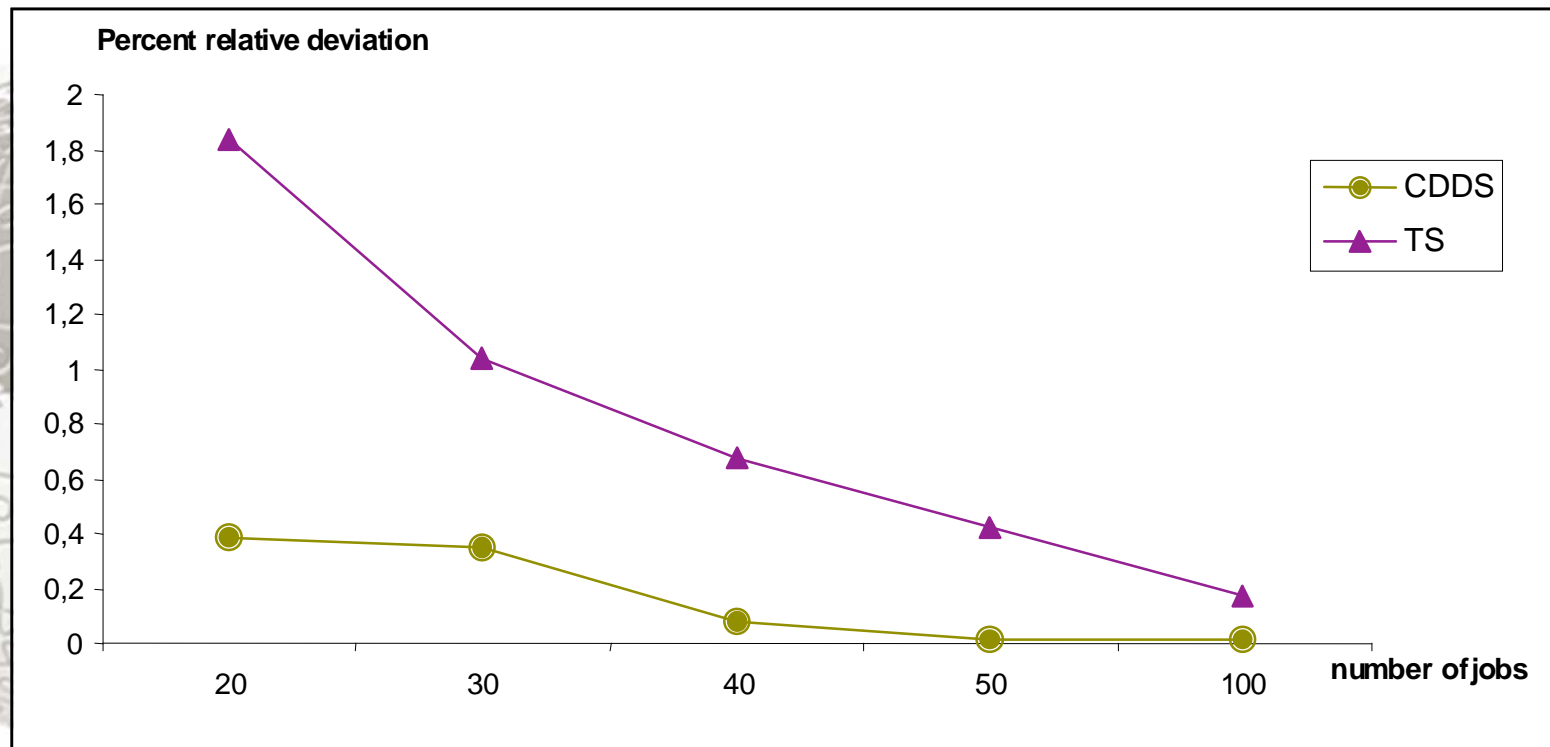
Relative performance of methods

<i>Method</i>	<i>Set A</i>	<i>Set B</i>	<i>Set C</i>
	<i>% deviation / LBs₂₀₀₆</i>		
CDDS^L	0.82	0.33	0.34
CDDS²	0.17	0.13	0.22
	<i>% deviation / LBs₁₉₉₇</i>		
TS	0.63	0.97	0.86
CDDS²	0.16	0.12	0.26

$$\% \text{ deviation} = \frac{C \max_best - \text{LowerBound}}{\text{LowerBound}} \times 100$$



2 stage-HFS: Experiments



FJS: Experiments

- Instances:
 - Brandimarte's benchmarks
 - 10 problems
 - $n=[10 - 20]$; $m=[4 - 15]$; $n_i=[5 - 15]$
- Comparison:
 - EDD is the best rule
 - Brandimarte's LBs
 - TS of [Mastrolilli & Gambardella, 2000] (M.G.)
- Stop: limit on CPU time=30 sec.

<i>instances</i>	<i>n</i>	<i>m</i>	<i>LB</i>	<i>M.G.</i>	<i>CDDS</i>	<i>%dev</i>	<i>CPU(M.G.)</i>	<i>CPU(CDDS)</i>
Mk01	10	6	36	40	40	0.0	0.01	0.1
Mk02	10	6	24	26	26	0.0	0.73	0.2
Mk03	15	8	204	204*	204*	0.0	0.01	0.2
Mk04	15	8	48	60	60	0.0	0.08	0.03
Mk05	15	4	168	173	182	5.2	0.96	0.2
Mk06	10	15	33	58	60	3.4	3.26	0.1
Mk07	20	5	133	144	139	-3.5	8.91	0.3
Mk08	20	10	523	523*	523*	0.0	0.02	0.8
Mk09	20	10	299	307	307	0.0	0.15	0.4
Mk10	20	15	165	198	212	7.1	7.69	0.3
Average						1.2	2.18	0.26



FJS: Experiments

- Instances:
 - Hurink's benchmarks
 - 129 problems (43 JSP): EData
RData
Vdata
 - n=[6 – 30]; m=[5 – 15]
- Comparison:
 - EDD is the best rule
 - [Pezella *et al.*, 2007]
 - Tabu + GA + LBs
- Stop:
 - limit on CPU time=30 sec.

Degree of flexibility ↓

- Mean relative error / best_LB):


Problems	Tabu (%)	CDDS (%)	GA (%)
EData	2.2	5.3	6.0
RData	1.2	2.5	4.4
VData	0.1	0.6	2.0

$$\% \text{ deviation} = \frac{C \max_best - \text{LowerBound}}{\text{LowerBound}} \times 100$$



FJS: Experiments

Deviation percentage over the best known lower bound



Data set	num	alt	CDDS (%)
Brandimarte	10	2.59	17.0
Hurink Edata	43	1.15	5.3
Hurink Rdata	43	2	2.5
Hurink Vdata	43	4.31	0.6

num: number of instances; alt: machine's number per job

Parallel machine scheduling

- Comparisons on $Pm|r_i, q_i|C_{\max}$ problems [Néron *et al.*, 2008]
(50 hard instances; $n = 100$, $m = 10$, $p_i = [1 - 10]$)
- Stop: limit on CPU time=30 sec.

$CPU_{limit} = 30\ s$	Best Solution	Best Sol. Strict	CPU(s)
$LDS_{z=1}^{TW}$	1	0	29.64
$LDS_{z=2}^{CHR}$	7	0	28.40
$BS_{\omega=3}^{TW}$	25	3	20.37
$BS_{\omega=4}^{CHR}$	22	0	28.40
CDS	35	6	30 (8.03)
HD-CDDS	38	9	30 (7.02)

Conclusions

- Novel method to solve Flexible Shop Problems:
 - CDDS: Climbing Depth-bounded Discrepancy Search
 - Hybrid Flow Shop
 - Excellent results - [Ben Hmida *et al.*, 2007; *EJIE*]
 - 2-stages - [Ben Hmida *et al.*, 2009; *JOS*, under review]
 - Flexible Job Shop (results to confirm)
 - Parallel machine (with precedence constraints and setup times, $L_{\max} ; \Sigma C_i$)
 - Excellent results - [Gacias *et al.*, 2009; *COR*, under review]



Further works

- FJS:
 - *Backjumping heuristic* on promising choice points for making discrepancies → concept of *Block neighborhoods* [Jurish, 1992]
 1. Permutation of two adjacent critical operations carried out by the same resource (discrepancy on selection variable)
 2. Re-assignment of a critical operation on another resource (discrepancy on allocation variable but restricted to critical operations)
 - Results improved [Ben Hmida *et al.* 2009, *in preparation*]

instances	#	<i>CDDS (old)</i>	<i>GA</i>	<i>TS</i>	<i>hGA</i>
<i>Brandimarte</i>	10	15.0 (17.0)	17.5	15.1	14.9
<i>Barnes/Chambers</i>	21	22.5 (nil)	29.6	22.5	22.6
<i>Hurink Edata</i>	43	2.3 (5.3)	6.0	2.2	2.1
<i>Hurink Rdata</i>	43	1.3 (2.5)	4.4	1.2	1.2
<i>Hurink Vdata</i>	43	0.1 (0.6)	2.0	0.1	0.08

Limit on CPU time=15 sec.

- Even better results on FJS (adapted lower bounds?)
- Extension to Multimode Resource-Constrained Project Scheduling Problems (MRCPPs)
- Multicriteria FJS ($\sum C_i$; L_{\max} – [Vilcot & Billaut, 2007])

